

# Regularity results for optimal patterns in the branched transportation problem

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# Outline

- 1 The functional
- 2 The landscape function
- 3 Fractal regularity

# Branched transportation problems

- Many natural systems show a distinctive tree-shaped structure: plants, trees, drainage networks, root systems, bronchial and cardiovascular systems.
- These systems could be described in terms of mass transportation, but Monge-Kantorovich theory turns out to be the wrong mathematical model since the mass is carried from the initial to the final point on a straight line.

# Branched transportation problems

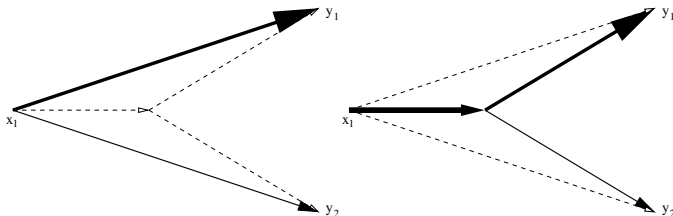
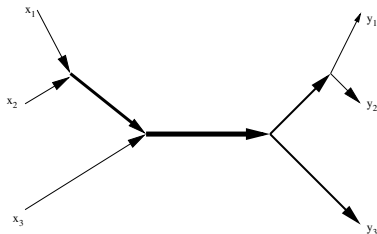


Figure: V-shaped versus Y-shaped transport.

## The functional (discrete case)

- $\Omega \subset \mathbb{R}^N$  compact, convex;
- $\mu^+ = \sum_{i=1}^m a_i \delta_{x_i}$ ,  $\mu^- = \sum_{j=1}^n b_j \delta_{y_j}$  convex combinations of Dirac masses;
- $G$  weighted directed graph;  $\text{spt } \mu^+, \text{spt } \mu^- \subseteq V(G)$ ;
- the mass flows from the initial measure  $\mu^+$  to the final measure  $\mu^-$  “inside” the edges of the graph  $G$ .



## The functional (discrete case)

- The point is now to provide to each transport path  $G$  a suitable cost that makes keeping the mass together cheaper. The right cost function is

$$J_\alpha(G) := \sum_{e \in E(G)} [m(e)]^\alpha l(e),$$

$l(e)$  length of edge  $e$ ,  $0 \leq \alpha < 1$  fixed;

- this cost takes advantage of the subadditivity of the function  $t \mapsto t^\alpha$  in order to make the tree-shaped graphs cheaper.

## The functional (continuous case)

- $e$  (oriented edge)  $\mapsto \mu_e = (\mathcal{H}^1|_e)\hat{e}$  (vector measure);
- $G \mapsto T_G = \sum_{e \in E(G)} m(e)\mu_e$ ;
- $\operatorname{div} T_G = \mu^+ - \mu^-$  sums up all conditions;
- a general **irrigation pattern** is defined by density and the cost as a lower semicontinuous envelope:

$$J_\alpha(T) = \inf_{T_{G_i} \rightarrow T} \liminf_{i \rightarrow +\infty} J_\alpha(T_{G_i}).$$

# The Irrigation Problem

## Problem (Irrigation problem)

- $\mu^+, \mu^-$  probability measures on  $\mathbb{R}^N$ ;
- minimize  $J_\alpha(G)$  among irrigation patterns  $G$  such that  $\operatorname{div} G = \mu^+ - \mu^-$ .

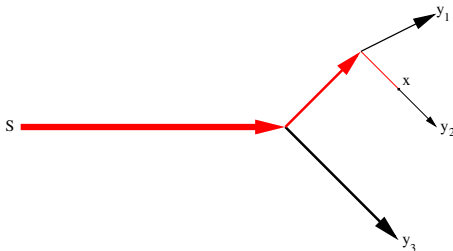
A pattern minimizing  $J_\alpha$  is the best branched structure between the source  $\mu^+$  and the irrigated measure  $\mu^-$ .



# The landscape function

$\mu^+ = \delta_S$ . For optimal graphs the landscape function  $Z$  is given by

$$Z(x) = \sum_{\text{path from } S \text{ to } x} [m(e)]^{\alpha-1} l(e).$$

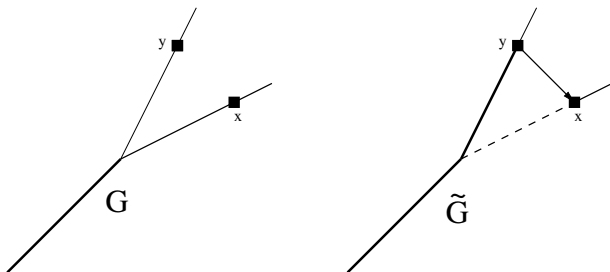


The landscape function can be defined also in the continuous setting.

# Why to consider the landscape function?

- In a discrete form, the landscape function was already introduced in geophysics and is related to the problem of erosion and landscape equilibrium;
- the landscape function is related to first order variations of the functional  $J_\alpha$ ;
- the Hölder regularity of landscape function is related to the decay of the mass on the paths of the graph.

# First order variations

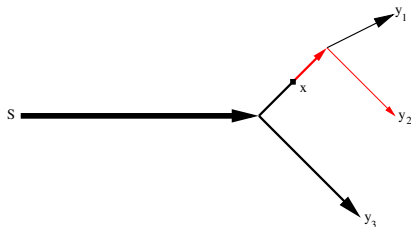


## Theorem (First order gain formula)

*The pattern  $\tilde{G}$  satisfies*

$$J_{\alpha}(\tilde{G}) - J_{\alpha}(G) \leq \alpha m(Z(y) - Z(x)) + m^{\alpha}|x - y|.$$

# Mass decay on the graph



## Theorem (Mass decay)

*Suppose that  $G$  is optimal. If  $Z$  is Hölder continuous of exponent  $\beta$ , then the mass decay exponent is  $(1 - \beta)/(1 - \alpha)$ :*

$$m(x) \gtrsim l(x)^{\frac{1-\beta}{1-\alpha}},$$

*and vice versa.*

# Hölder continuity when the irrigated measure is LAR

## Definition

A measure  $\mu$  is **lower Ahlfors regular** in dimension  $h$  if there exist  $r_0 > 0$  and  $c_A > 0$  such that:

$$\mu(B_r(x)) \geq c_A r^h \text{ for all } x \in \text{spt } \mu \text{ and } 0 < r < r_0.$$

## Theorem

*Suppose that the irrigated measure is LAR in dimension  $h$ . Then, the landscape function  $Z$  is Hölder with exponent  $\beta = 1 + h(\alpha - 1)$ .*

Some example shows that the landscape regularity may be better and may depend on the source of irrigation.

# Best estimate on the Hölder exponent

## Definition

A measure  $\mu$  is **upper Ahlfors regular** in dimension  $h$  if there exists  $C_A > 0$  such that:

$$\mu(B_r(x)) \leq C_A r^h \text{ for all } r > 0.$$

## Theorem

*Suppose that the irrigated measure is UAR above in dimension  $h$  and the landscape function  $Z$  is Hölder with exponent  $\beta$ . Then,  $\beta \leq 1 + h(\alpha - 1)$ .*

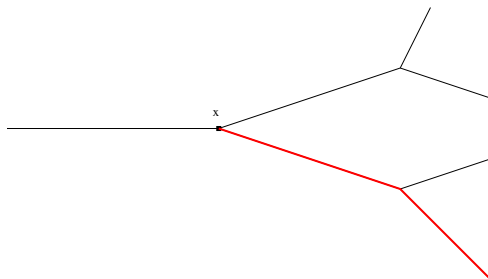
If the irrigated measure is Ahlfors regular in dimension  $h$  (both LAR and UAR), the best Hölder exponent is  $1 + h(\alpha - 1)$ .

# Main branches from a point

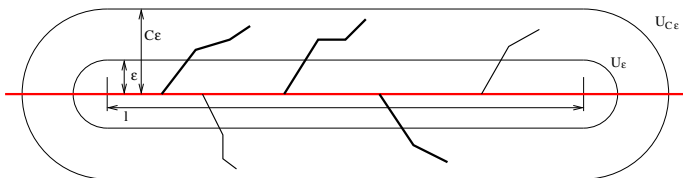
In the next the irrigated measure will always be *Ahlfors regular* in dimension  $h$ .

**Definition (Main branches from a point  $x$ )**

A *main branch* starting from a point  $x$  is the branch maximizing the residual length.



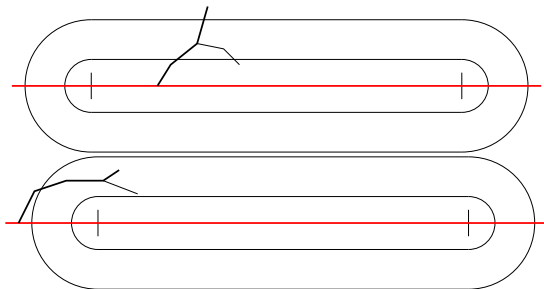
# Fractal regularity



- $N$  = number of branches bifurcating of residual length between  $\varepsilon$  and  $C\varepsilon$ .
- mass carried by one of such branches  $\gtrsim \varepsilon^h$ ,
- mass of the tubular neighbourhood of radius  $C\varepsilon \sim l\varepsilon^{h-1}$ ,
- mass balance:  $\varepsilon^h N \lesssim l\varepsilon^{h-1}$ ,
- $N \lesssim \frac{l}{\varepsilon}$ .



# Fractal regularity



It can be proved that for small  $\varepsilon$  and a suitable choice of  $C$  the measure irrigated by “long branches” and by “far away branches” is a fraction of the measure of  $U_{C\varepsilon} \setminus U_\varepsilon$ . Then, we also have

$$N \gtrsim \frac{1}{\varepsilon}.$$

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